nexen

## WEB CONTROL PRODUCTS

User Manual

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# Dancer Position Sensor DPS30 and DPS60 

In accordance with Nexen's established policy of constant product improvement, the specifications contained in this manual are subject to change without notice. Technical data listed in this manual are based on the latest information available at the time of printing and are also subject to change without notice.

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## DANGER

Read this manual carefully before installation and operation.
Follow Nexen's instructions and integrate this unit into your system with care.
This unit should be installed, operated and maintained by qualified personnel ONLY.
Improper installation can damage your system or cause injury or death.
Comply with all applicable codes.


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## INTRODUCTION

Nexen Dancer Position Sensors have been designed to accurately measure the rotational movement of a dancer arm. This family of sensors use Hall Effect technology which provide for benefits such as infinite resolution, low drag, and no mechanical wear. They are ideally suited to work with Nexen's Dancer Position Controllers.

## INSTALLATION

NOTE: Mounting of the Dancer Position Sensor can be accomplished two ways. The first is the Direct Connection method and the second is the Stub Shaft Connection method. Review the instructions for both methods and select the method best suited for your application.

## DIRECT CONNECTION

1. Verify that the dancer arm pivot shaft's end complies with the dimensions given (See Figure 1).
2. The orientation of the Dancer Position Sensor (Item 1) must be as shown in order to match the mid output of the Dancer Position Sensor to the mid travel position of the dancer arm (See Figure 2).
3. Attach Dancer Position Sensor (Item 1) to the Bracket (Item 2) with the Long Pan Head Screws (Item 3), Flat Washers (Item 4), Lock Washers (Item 5), and Nuts (Item 6) (See Figure 3).
4. Align Dancer Position Sensor (Item 1) with the center of the slots in the Bracket (Item 2) and then hand tighten just enough to prevent it from moving during Steps 5, 6, and 7 (See Figure 3).
5. With the dancer arm held firmly in its mid travel position, slide the Dancer Position Sensor (Item 1) over the shaft while carefully aligning the key with the shaft's key way (See Figure 3).
6. Slide the Dancer Position Sensor (Item 1) onto the shaft until the Bracket (Item 2) contacts the machine's side frame (See Figure 3).
7. Mark the location of the Bracket's two mounting holes.
8. Remove the Dancer Position Sensor (Item 1) and Bracket (Item 2); then, drill and tap two 8-32 threaded holes centered within the marks drawn in Step 7.
9. Slide the Dancer Position Sensor (Item 1) onto the shaft while carefully aligning the key and key way.


Figure 3
8. Insert one Short Pan Head Screw (Item 7) into the green wire's ring terminal.
9. Using both Short Pan Head Screws (Item 7) and Lock Washers (Item 5), secure the Bracket (Item 2) to the machine's side frame (See Figure 3).

## STUB SHAFT CONNECTION

1. Purchase a zero backlash flexible shaft coupler that accommodates the diameter of the Stub Shaft ( Item 8) on one end and the dancer arm pivot shaft on the other end (See Figures 4 and 9).
2. Slide the shaft coupler onto the dancer arm pivot shaft, inserting the shaft no further than half the thickness of the coupler clamp; then, tighten the clamp around the shaft (See Figure 4).
3. Slide the Stub Shaft (Item 8) into the shaft coupler, inserting the Stub Shaft no further than half the thickness of the coupler clamp; then, tighten the clamp around the Stub Shaft (See Figure 4).
4. Position the Dancer Arm in its mid-travel position.
5. The orientation of the Dancer Position Sensor (Item 1) must be as shown in order to match the mid output of the Dancer Position Sensor to the mid travel position of the dancer arm (See Figure 5).
6. Attach Dancer Position Sensor (Item 1) to the Bracket (Item 2) with the Long Pan Head Screws (Item 3, Flat Washers (Item 4), Lock Washers (Item 5), and Nuts (Item 6) (See Figure 4).
7. Align Dancer Position Sensor (Item 1) with the center of the slots in the Bracket (Item 2) and then hand tighten just enough to prevent sensor from moving during Steps 8 and 9 (See Figure 4).
8. With the dancer arm held firmly in its mid travel position, slide the Dancer Position Sensor (Item 1) over the Stub Shaft (Item 8) while carefully aligning the key with the shaft's key way (See Figure 4).
9. Slide the Dancer Position Sensor (Item 1) onto the Stub Shaft (Item 8); then, measure the distance from the bottom of the Bracket (ltem 2) to the machine's side frame. Fabricate a spacer block to make up the distance between the Bracket and the machine's side frame (See Figure 4).
10. Repeat Steps $\mathbf{8}$ and $\mathbf{9}$ with the spacer block in place on the machine's side frame and mark the location for the bracket's mounting holes.
11. Remove the Dancer Position Sensor (Item 1) and Bracket (Item 2); then, drill and tap two 8-32 threaded holes centered within the marks drawn in Step 10.
12. Slide the Dancer Position Sensor (Item 1) onto the


Figure 4


Stub Shaft (Item 8) while carefully aligning the key and key way.
13. Insert one customer supplied 8-32 screw into the green wire's ring terminal.
14. Using customer supplied 8-32 screws and lock washers, secure the Bracket (Item 2) to the customer supplied spacer block and the machine's side frame (See Figure 4).

## ELECTRICAL CONNECTIONS

1. Route the Dancer Position Sensor signal cable through the machine.
2. Connect the signal cable to a controller (See Figure 6).

NOTE: The signal cable's shield must be earth grounded through the green wire to the machine. The shield drain wire at the other end of the signal cable should be earth grounded only if noise is present on the position signal.


Figure 6

## ADJUSTMENT

1. Apply power to the Dancer Position Sensor.
2. Using a voltmeter, measure the voltage across the brown (+) and the blue (-) wires (See Figure 6). Voltmeter must match the supply voltage for proper operation (see specifications).
3. Attach the (+) lead to the signal wire from the sensor (See Figure 6).
4. Move the dancer arm through its full range. While the dancer arm is moving, the sensor output voltage should change. If output voltage stops changing as the dancer arm is moving, slightly loosen the sensor's fasteners and rotate the sensor.
5. Tighten the fasteners securely to prevent the Dancer

Position Sensor from moving.
6. Trim back any unused wires to prevent electrical shorting problems.
7. At this time the installation and adjustment of the Nexen Dancer Position Sensor is complete.

| SYMPTOM | PROBABLE CAUSE | SOLUTION |
| :---: | :---: | :---: |
| No voltage from Dancer Position Sensor. | No power to the Dancer Position Sensor. | Turn on the power to the Dancer Position Controller. Connect the Dancer Position Sensor according to Figure 6. |
|  | Input power polarity is backwards. | Replace Dancer Position Sensor and connect it according to Figure 6. |
| Dancer Position Sensor output does not change. | No power to the Dancer Position Sensor. | Turn on the power to the Dancer Position Controller. Connect the Dancer Position Sensor according to Figure 6. |
|  | Dancer Position Sensor misaligned. | Align the Dancer Position Senso according to Figure 2 for Mid Point of Output and according to the instructions in the INSTALLATION, and ADJUSTMENT Sections. |
|  | Dancer arm exceeds the capability of the sensor. | Switch to a DPS60 or restrict the swing of the dancer arm. Refer to SPECIFICATIONS. |
| Dancer Position Sensor output voltage swing is backwards in relation to the dancer arm movement. | Orientation of the dancer arm components on the machine. | Use the second position signal wire. |
| Position Sensor Signal is erratic with no dancer arm movement. | Electrical noise interferring with sensor. | Connect green wire to earth ground. If noise persists, then connect the shield's drain wire to earth ground. |
| Dancer Position Sensor output voltage not changing through full 30-degree or 60-degree range. | Dancer Position Sensor misaligned. | Refer to Figure 2. Rotate sensor 180 degrees so key way is aligned properly. |

## DANCER POSITION SENSOR



## BRACKET

Figure 10



Figure 11

| ITEM | DESCRIPTION | QTY |
| :---: | :---: | :---: |
| 1 | Dancer Position Sensor | 1 |
| 2 | Bracket | 1 |
| 3 | Pan Head Phillips Screw | 2 |
| 4 | Flat Washer | 2 |


| ITEM | DESCRIPTION | QTY |
| :---: | :---: | :---: |
| 5 | Lock Washer | 4 |
| 6 | Hex. Nut | 2 |
| 7 | Pan Head Phillips Screw | 2 |
| 8 | Stub Shaft | 1 |

## REPLACEMENT PARTS

The item or balloon number for all Nexen products is used for part identification on all product parts lists, product price lists, unit assembly drawings, bills of materials, and instruction manuals.

When ordering replacement parts, specify model designation, item number, part description, and quantity. Purchase replacement parts through your local Nexen Distributor.

## SPECIFICATIONS

|  | DPS30 |  |
| :--- | :---: | :---: |
| Product Number | 964510 | 964515 |
| Supply Voltage | 11.5 to 12.5 VDC | 22 to 26VDC |
| Output Voltage | $0 \sim 10 \mathrm{VDC}$ or $10 \sim 0 \mathrm{ODC}$ <br> @ max. angular rotation |  |
| Reverse Polarity Protection | -30 VDC maximum |  |
| Temperature | $-40^{\circ} \mathrm{F}\left[-40^{\circ} \mathrm{C}\right]$ to $176^{\circ} \mathrm{F}\left[80^{\circ} \mathrm{C}\right]$ |  |
| Enclosure | NEMA 4 |  |
| Resolution | Infinite |  |
| Angular Rotation | $+/-15^{\circ}$ maximum |  |


|  | DPS60 |  |
| :---: | :---: | :---: |
| Product Number | 964511 | 964516 |
| Supply Voltage | 11.5 to 12.5 VDC | 22 to 26 VDC |
| Output Voltage | 0~10VDC or 10~0VDC <br> @ max. angular rotation |  |
| Reverse Polarity Protection | -30VDC maximum |  |
| Temperature | $-40^{\circ} \mathrm{F}\left[-40^{\circ} \mathrm{C}\right]$ to $176{ }^{\circ} \mathrm{F}\left[80^{\circ} \mathrm{C}\right]$ |  |
| Enclosure | NEMA 4 |  |
| Resolution | Infinite |  |
| Angular Rotation | +/-30 ${ }^{\circ}$ maximum |  |

## Warranties

Nexen warrants that the Products will be free from any defects in material or workmanship for a period of 12 months from the date of shipment. NEXEN MAKES NO OTHER WARRANTY, EXPRESS OR IMPLIED, AND ALL IMPLIED WARRANTIES, INCLUDING WITHOUT LIMITATION, IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE HEREBY DISCLAIMED. This warranty applies only if (a) the Product has been installed, used and maintained in accordance with any applicable Nexen installation or maintenance manual for the Product; (b) the alleged defect is not attributable to normal wear and tear; (c) the Product has not been altered, misused or used for purposes other than those for which it was intended; and (d) Buyer has given written notice of the alleged defect to Nexen, and delivered the allegedly defective Product to Nexen, within one year of the date of shipment.

## Exclusive Remedy

The exclusive remedy of the Buyer for any breach of the warranties set out above will be, at the sole discretion of Nexen, a repair or replacement with new, serviceably used or reconditioned Product, or issuance of credit in the amount of the purchase price paid to Nexen by the Buyer for the Products.

## Limitation of Nexen's Liability

TO THE EXTENT PERMITTED BY LAW NEXEN SHALL HAVE NO LIABILITY TO BUYER OR ANY OTHER PERSON FOR INCIDENTAL DAMAGES, SPECIAL DAMAGES, CONSEQUENTIAL DAMAGES OR OTHER DAMAGES OF ANY KIND OR NATURE WHATSOEVER, WHETHER ARISING OUT OF BREACH OF WARRANTY OR OTHER
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## Limitation of Damages

In no event shall Nexen be liable for any consequential, indirect, incidental, or special damages of any nature whatsoever, including without limitation, lost profits arising from the sale or use of the Products.

## Warranty Claim Procedures

To make a claim under this warranty, the claimant must give written notice of the alleged defect to whom the Product was purchased from and deliver the Product to same within one year of the date on which the alleged defect first

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